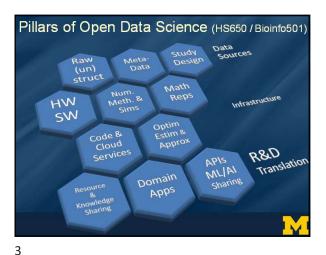


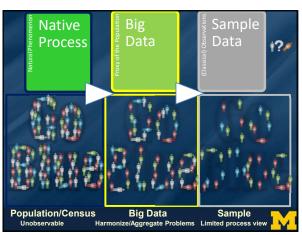
Outline ☐ Pillars of Open-Science ☐ Rationale (Pros & Cons) Big Data Sharing ■ DataSifter: Statistical obfuscation Case-studies □ ALS Study ☐ Population Census-like Neuroscience (UKBB) ■ Spacekime Analytics

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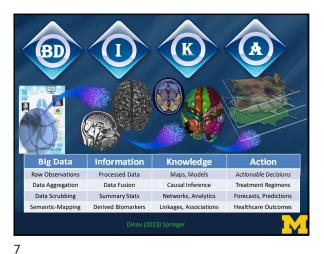
Sources: Characteristics of Big Biomed Data IBM Big Data 4V's: Volume, Variety, Velocity & Veracity Big Bio Data Dimensions Example: analyzing observational data of 1,000's Parkinson's disease patients based on 10,000's Harvesting and management of vast amounts of data Size signature biomarkers derived from multi-source imaging, genetics, clinical, physiologic, phenomics and Wranglers for dealing with heterogeneous data Complexity Tools for data harmonization and demographic data elements Incongruency Transfer and joint modeling of disparate elements Software developments, student Multi-source training, service platforms and methodological advances associated with the Big Data Discovery Science all present existing opportunities for learners Techniques accounting for Time longitudinal patterns in the data educators, researchers, practitioners and policy makers Reliable management of missing Incomplete

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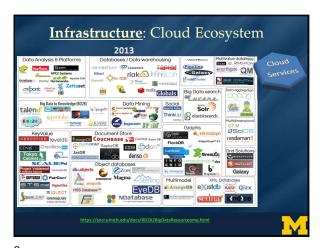


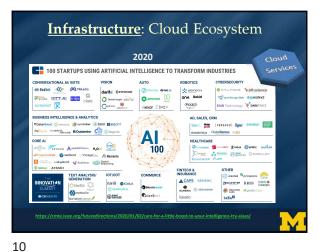
From 23 ... to ... 2²³ ☐ Data Science: 1798 vs. 2024 ☐ In the 18th century, Henry Cavendish used just 23 observations to answer a fundamental question – "What is the Mass of the Earth?" He estimated very accurately the mean density of the Earth/H₂O (5.483±0.1904 g/cm³) ☐ In the 21st century to achieve the same scientific impact, matching the reliability and the precision of the Cavendish's 18th century prediction, requires a monumental community effort using massive and complex information perhaps on the order of 223 bytes □ Data & Information Science ≅ Scalability & Compression (per Gerald Friedland/Berkeley): 23 → 2²³ ≅ 10M

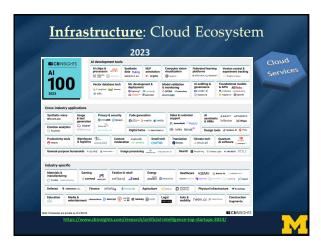
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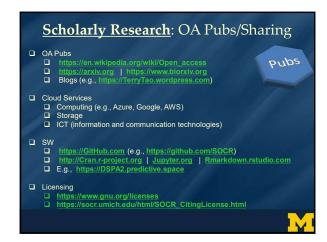


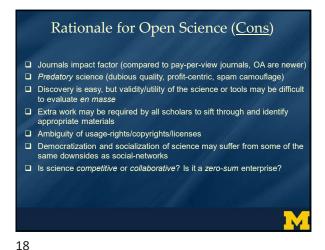


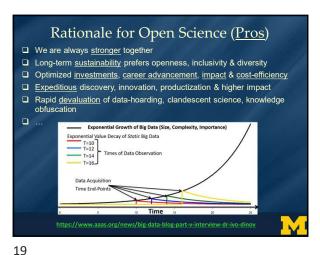








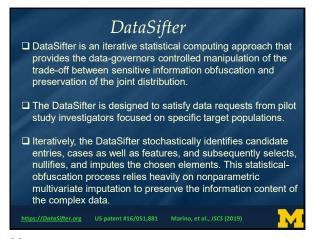


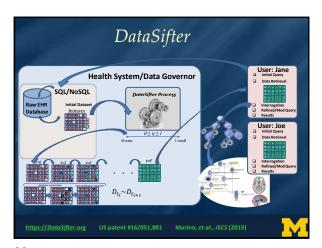


Rationale for Open Science: Kryder vs. Moore ☐ Moore's law = the expectation that our computational capabilities, specifically the number of transistors on integrated circuits, doubles approximately every 18-24 ☐ Kryder's law = the volume of data, in terms 10000000 of disk storage capacity, is doubling every 5000000 14-18 months. ☐ Kryder ≫ Moore: Although both laws yield exponential growth, data volume is increasing at a faster pace. Thus, there are clear interests and needs for significant private, public and government engagement in opening, managing, processing, interrogating and interpreting the information content of Big Data.

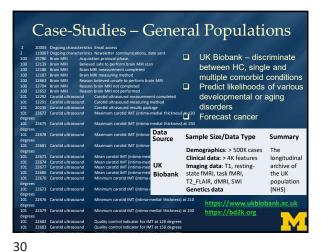


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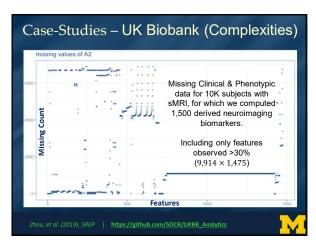


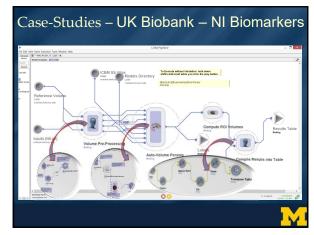




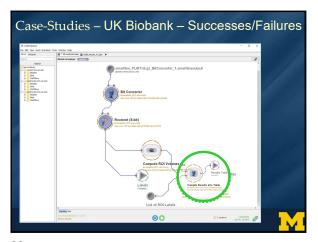


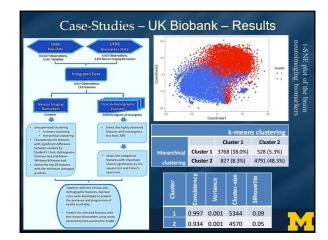
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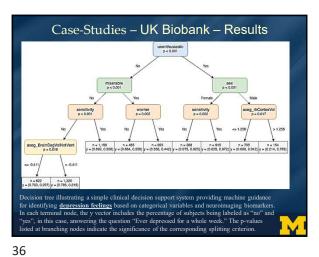


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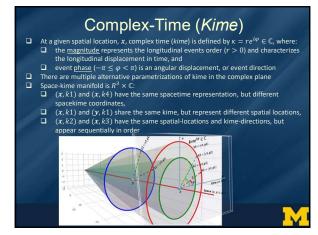


Case	e-Stu	dies -	– UK Biobank –	Result	S
Variable Ne Penale Male Tending Net Tening Ye No Water Consists Services	1,350 (26.7%) 3,661 (75.8%) 2,562 (67.8%) 2,362 (12.2%)	4,063 (No.) 1,257 (24.) 1,031 (No.) 2,331 (EL.)			
Tes No. No. Nos Lakag Yes	2,375 (48.2%) 2,877 (13.8%) 1,878 (13.0%)	2,995 (32.6) 2,208 (42.6) 1,354 (22.6)	Variable	Cluster 1	Cluster 2
No Quilty Seelings Yes The Seelings Sees distinctor names, and rig tanking or department Yes The	1,000 (69.0%) 1,000 (36.0%) 3,617 (75.0%) 1,011 (29.0%)	1,981 (77. 1,987 (32. 1,386 (47. 1,985 (37.	Sex Female Male	1,134 (24.7%) 3,461 (75.3%)	4,062 (76.4%) 1,257 (23.6%)
No New Manager States with meast Yes No New Yes	1,317 (10.76) 1,354 (66.76) 904 (38.39) 1,796 (41.76)	2,500 (No.) 273 (28.40 1602 (18.40			1,237 (23.076)
No. Were two long after enthanassment Tes No. Manufactures	2,577 (18.9%) 1,978 (46.9%) 2,491 (19.7%)	2,826 (86.11) 2,675 (32.11) 2,662 (87.11)	Nervous feelings Yes No	751 (16.6%) 3.763 (83.4%)	1,071 (20.8%)
Yes No Teachighty solidate/argumentation for Y days Yes No November trailings	1,723 (27.7%) 2,829 (62.8%) 685 (22.7%) 4,088 (89.8%)	2,882 (94. 2,882 (94. 289 (26.39) 4,628 (81.3)		3,763 (83.4%)	4,076 (79.2%)
Test	752 (28.6%) 3,768 (83.6%) 2,376 (68.2%) 2,367 (53.5%)	1,071 (20.1) 4,076 (76.1) 2,789 (32.1) 2,488 (67.1)	Frequency of tiredness/lethargy in last 2 weeks		
The Committee of the American Committee of the Committee	1,806 (80.86) 3,009 (60.76) 1,807 (29.86)	3,761 (M. II) 3,861 (M. II) 1,861 (M. II)	Not at all Several days	2,402 (53.0%) 1,770 (39.0%)	2,489 (47.8%) 2,127 (40.9%)
Simulation County Dividing Gentling to Minimize Red of all easy Not sery easy	2,302 (47.8%) 1,636 (22.8%) 189 (12.9%)	2,372 (88-1) 2,363 (28-1) 201 (4.7% 830 (23.8)	More than half the days Nearly everyday	187 (4.1%1) 177 (3.9%)	300 (5.8%) 287 (5.5%)
Notice and Table	2,827 (11.01) 1,836 (18.71) 2,017 (16.311) 1,751 (18.81)	2,663 (503) 1,505 (283) 3,208 (613) 1,798 (643)	Alcohol drinker status Never Previous	81 (1.8%) 83 (1.8%)	179 (3.4%) 146 (2.7%)
Visally Frequency of the deepy in that 2 weeks Not at all Second days Note than half the days	2,622 (18.0%) 2,622 (18.0%) 1,750 (181.0%) 187 (6.1%2)	22K (4.8% 2,689 (27.2) 2,127 (601) 800 (1.8%	Current	4,429 (96.4%)	4,992 (93.9%)
Ready everyday Acute denter status News Previous Curent	177 (1.9%) 81 (1.8%) 83 (1.8%) 4,479 (96.6%)	287 (1.0% 179 (1.0% 300 (2.79			

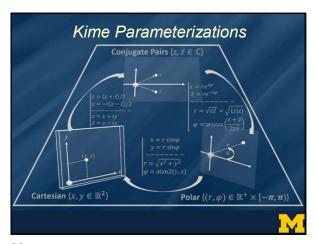


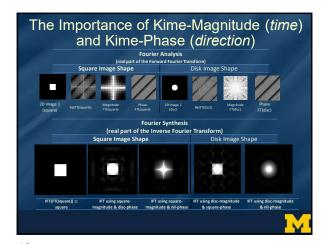
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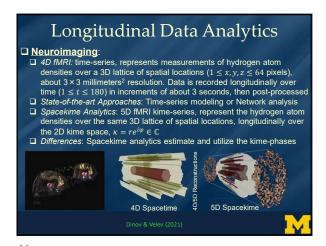
	Accuracy	95% CI (Accuracy)	Sensitivity	Specificity
Sensitivity/hurt feelings	0.700	(0.676, 0.724)	0.657	0.740
Ever depressed for a whole week	0.782	(0.760, 0.803)	0.938	0.618
Worrier/anxious feelings	0.730	(0.706, 0.753)	0.721	0.739
Miserableness	0.739	(0.715, 0.762)	0.863	0.548
Cross-validated (randon		prediction resu disorders	ılts for fou	ır types



37 38







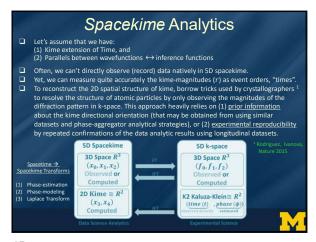
Spacekime Calculus

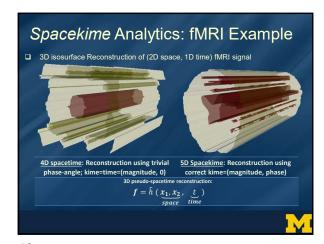
| Kime Wirtinger derivative (first order kime-derivative at $k=(r,\varphi)$):
In Cartesian coordinates: $f'(z) = \frac{\partial f(z)}{\partial z} = \frac{1}{2} \left(\frac{\partial f}{\partial x} - i\frac{\partial f}{\partial y}\right) \text{ and } f'(\bar{z}) = \frac{\partial f(z)}{\partial z} = \frac{1}{2} \left(\frac{\partial f}{\partial x} + i\frac{\partial f}{\partial y}\right).$ In Conjugate-pair basis: $df = \partial f + \bar{\partial} f = \frac{\partial f}{\partial z} dz + \frac{\partial f}{\partial z} d\bar{z}.$ In Polar kime coordinates: $f'(k) = \frac{\partial f(k)}{\partial k} = \frac{1}{2} \left(\cos \varphi \frac{\partial f}{\partial r} - \frac{1}{r} \sin \varphi \frac{\partial f}{\partial \varphi} - i \left(\sin \varphi \frac{\partial f}{\partial r} + \frac{1}{r} \cos \varphi \frac{\partial f}{\partial \varphi}\right)\right) = \frac{e^{-i\varphi}}{2} \left(\frac{\partial f}{\partial r} - i\frac{\partial f}{\partial \varphi}\right).$ $f'(k) = \frac{\partial f(k)}{\partial k} = \frac{1}{2} \left(\cos \varphi \frac{\partial f}{\partial r} - \frac{1}{r} \sin \varphi \frac{\partial f}{\partial \varphi} + i \left(\sin \varphi \frac{\partial f}{\partial r} + \frac{1}{r} \cos \varphi \frac{\partial f}{\partial \varphi}\right)\right) = \frac{e^{i\varphi}}{2} \left(\frac{\partial f}{\partial r} - i\frac{\partial f}{\partial \varphi}\right).$ | Kime Wirtinger integration: $Path-integral \lim_{|z|_{+1}-z|_{+1}-0} \sum_{i=1}^{n-1} (f(z_i)(z_{i+1}-z_i)) \cong \oint_{z_d}^{z_b} f(z_i)dz.$ $Definite area integral: \int f \Omega \subseteq \mathbb{C}, \int_{\Omega} f(z)dzd\bar{z}.$ $Indefinite integral: \int f(z)dzd\bar{z}, df = \frac{\partial f}{\partial z}dz + \frac{\partial f}{\partial z}d\bar{z}.$ The Laplacian in terms of conjugate pair coordinates is $\Delta f = d^2 f = 4\frac{\partial f}{\partial z}d\bar{z} = 4\frac{\partial f}{\partial z}d\bar{z}$

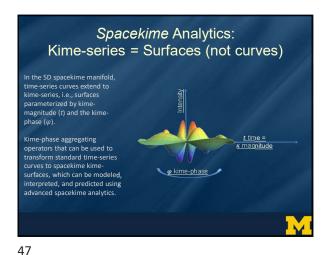
41 42

Mathematical-Physics	Data Science		
A particle is a small localized object that	An object is something that exists by itself, actually or		
permits observations and characterization of	potentially, concretely or abstractly, physically or		
its physical or chemical properties	incorporeal (e.g., person, subject, etc.)		
An observable a dynamic variable about	A feature is a dynamic variable or an attribute about an		
particles that can be measured	object that can be measured		
Particle state is an observable particle	Datum is an observed quantitative or qualitative value,		
characteristic (e.g., position, momentum)	an instantiation, of a feature		
Particle system is a collection of	Problem, aka Data System, is a collection of		
independent particles and observable	independent objects and features, without necessarily		
characteristics, in a closed system	being associated with a priori hypotheses		
Wave-function	Inference-function		
Reference-Frame transforms (e.g., Lorentz)	Data transformations (e.g., wrangling, log-transform)		
State of a system is an observed	Dataset (data) is an observed instance of a set of		
measurement of all particles ~ wavefunction	datum elements about the problem system, $0 = \{X, Y\}$		
A particle system is computable if (1) the	Computable data object is a very special		
entire system is logical, consistent, complete	representation of a dataset which allows direct		
and (2) the unknown internal states of the	application of computational processing, modeling,		
system don't influence the computation	analytics, or inference based on the observed dataset		
(wavefunction, intervals, probabilities, etc.)			

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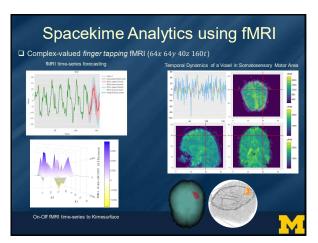


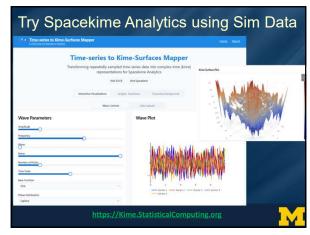




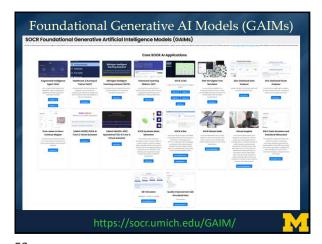
Bayesian Inference Representation ☐ We can formulate spacekime inference as a Bayesian parameter estimation problem: $\frac{p(y|X, \varphi')}{\text{prior distribution}} = \frac{p(y, X, \varphi')}{p(X, \varphi')} = \frac{p(X|y, \varphi') \times p(y, \varphi')}{p(X, \varphi')} = \frac{p(X|y, \varphi') \times p(y, \varphi')}{p(X|\varphi') \times p(\varphi')} = \frac{p(X|y, \varphi') \times p(\varphi')}{p(X|\varphi') \times p(\varphi')} = \frac{p(X|y, \varphi') \times p(y, \varphi')}{p(X|\varphi') \times p(\varphi')} = \frac{p(X|y, \varphi') \times p(y, \varphi')}{p(X|\varphi')} = \frac{p(X|y, \varphi')}{p(X|\varphi')} = \frac{$ $\begin{array}{ll} p(\gamma|X,\varphi') & \equiv & p(X,\varphi') & p(x,\varphi') \\ \text{terior distribution} & & p(y,\varphi') & p(x,\varphi') \\ & = & \frac{p(X|\gamma,\varphi')}{p(X|\varphi')} \times \frac{p(\gamma,\varphi')}{p(\varphi')} & = & \frac{p(X|\gamma,\varphi') \times p(\gamma|\varphi')}{p(X|\varphi')} \propto & \frac{p(X|\gamma,\varphi')}{\text{likelihood}} \times \underbrace{p(\gamma|\varphi')}_{\text{prior}} \end{array}$ In Bayesian terms, the posterior probability distribution of the unknown parameter γ is proportional to the product of the likelihood and the prior. $\hfill \square$ In probability terms, the posterior = likelihood times prior, divided by the observed evidence, in this case, a single spacetime data point, $x_{l_0}.$

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