

# Kime-Phase Tomography (KPT)

Manifold Representation of Longitudinal Processes over a Complex-Time Domain

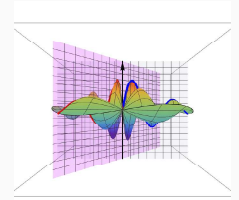
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<https://SOCR.umich.edu> | <https://TCIU.predictive.space/>



## Outline

1. Motivation and Problem Setting
2. Mathematical Foundations
3. Inference and Space-Kime Analytics
4. Applications and Validation (Simulations)
5. Limitations and Opportunities
6. Summary



Kime-Surface Representation

## 1. Motivation and Problem Setting

Idea: Longitudinal Data → Kime-Transforms → PDEs → AI/ML

| Apps    | Time → Kime Transformation                | Wave equation Solutions (kime) dynamics                                     | Prospective Data Science Applications    |
|---------|---|---|--|
| Biomed  | fMRI time-series                          | fMRI kime-surfaces  | Cross sections                           |
|         | X-ray Diffraction (XRD) Crystallography   | XRD Signal  | Volume rendering                         |
| Physics | Time-dynamic structural phase transitions | Wavelet or Hilbert transform of time-dependent diffraction                  | 3D p-value map                           |
|         |   |   | Stat significance                        |
|         |   | Time-Frequency Analysis   | Bayesian Reconstr. Strain Field          |
|         |   | 2D Dislocation Strain Field   | Predict strain fields or defect dynamics |
|         |   | Takagi-Taupin PDE model of dynamical X-ray diffraction in deformed crystals | Mechanical Change Detection (CMR + 0.05) |
|         |   | Phonon modes at phase transition  |  |

## Why kime? Why tomography?

- **Observed problem:** repeated measurements at the same chronological time often exhibit large *structured* variability (not just additive noise).
- **Consequence:** averaging/denoising can erase latent state structure, leading to miscalibrated inference or degraded prediction.
- **KPT goal:** decompose replicate variability into
  - extrinsic (range-space) noise + intrinsic (domain-space) phase variability.
- **Kime representation:** augment time  $t$  by a latent phase  $\theta \in \mathbb{S}^1$ , forming a complex-time coordinate
 
$$\kappa = t e^{i\theta} \in \mathbb{C},$$
 enabling *phase-resolved* inference and prediction.

## Rationale for Time → Kime Extension

- **Math:** *Time* is a special case of *Kime*,  $\kappa = t e^{i\theta} \in \mathbb{C}$ , where  $\theta = 0$ . Time ( $\mathbb{R}^+$ ) is a subgroup of the multiplicative Reals group. Whereas kime ( $\mathbb{C}$ ) is an algebraically closed field that naturally extends time. Time is ordered, kime is not! As a complete field, *Kime* represents the smallest natural extension of *Time*.
- **Physics:**
  - The *Problem of Time*: Time has different meanings in quantum mechanics & general relativity; leading to a tension in formulating a Quantum Gravity Theory unifying the two (DOI 10.1007/978-3-319-58848-3).
  - (Base-field)  $\mathbb{R}$  and  $\mathbb{C}$  based Hilbert-space quantum theories make different predictions (DOI: 10.1038/s41586-021-04160-4).
- **AI/Data Science:** Random IID sampling, Bayesian representations, tensor modeling of  $\mathbb{C}$  kimesurfaces & novel analytics.

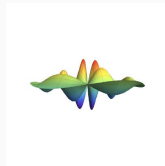
Wesson (2010); Dinov & Velev (2021); Wang et al. (2022); Zhang et al. (2023); Dinov & Shen (2024).

## KPT data model (replicated longitudinal processes)

For time points  $t_k \in (0, T]$  and replicates  $j = 1, \dots, N$ :

$$\underbrace{\Theta_{j,k}}_{\text{stochastic phase}} \sim \underbrace{\varphi_{t_k}(\theta)}_{\text{latent phase law on } \mathbb{S}^1}$$

$$\underbrace{y_{j,k} | \Theta_{j,k}}_{\text{observed measurements}} \sim p(y | \theta; t_k, \mathcal{S})$$



Model Kime-Surface

A common likelihood (used in simulations and algorithms):

$$y_{j,k} = \mathcal{S}(t_k, \Theta_{j,k}) + \varepsilon_{j,k}, \quad \varepsilon_{j,k} \sim \mathcal{N}(0, \sigma^2).$$

**Unknown objects:**

kime-surface  $\mathcal{S}(t, \theta)$  and phase density  $\varphi_t(\theta) \in \mathcal{P}$ .

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## Problem Solved by Kime-Phase Tomography (KPT)

### KPT capability

Given replicated longitudinal observations  $\{y_{j,k}\}$ , KPT reconstructs a coupled pair

$$(\hat{\mathcal{S}}(t, \theta), \hat{\varphi}_t(\theta))$$

that explains structured replicate-to-replicate variability as a time-evolving phase distribution on  $\mathbb{S}^1$ .

- **Interpretability:**  $\hat{\varphi}_t$  quantifies latent state concentration, drift, multimodality.
- **Prediction:** synthetic draws  $\theta \sim \hat{\varphi}_t$  and evaluation of  $\hat{\mathcal{S}}(t, \theta)$  induce predictive distributions.
- **Scalability:** FFT-based spectral updates enable fast inference on dense time grids.

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## 2. Mathematical Foundations

## Historical Background: Kaluza-Klein Theory

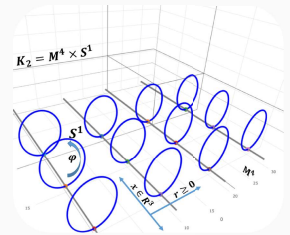
Theodor Kaluza (1921) developed a *math extension of the classical general relativity theory to 5D*. This included the metric, the field equations, the stress-energy tensor, and the cylinder condition.

Physicist Oskar Klein (1926) *interpreted Kaluza's 3D+2D theory in quantum mechanical space* and proposed that the fifth dimension was curled up and microscopic.

The topology of the 5D Kaluza-Klein spacetime is  $\mathbb{K}_2 \simeq \mathbb{M} \times \mathbb{S}^1$ , where  $\mathbb{M}$  is a 4D Minkowski spacetime and  $\mathbb{S}^1$  is a circle (non-traversable).

(Kaluza) DOI: 10.1142/S0218271818700017; (Klein) DOI: 10.1007/BF01397481; (Bailin & Love) DOI: 10.1088/0034-4885/50/9/001

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## Ultrahyperbolic PDEs: Wave Equation – Cauchy Initial Data

For ultrahyperbolic PDEs, the (*unconstrained*) initial value problem, determining the solution(s) for a given initial condition, is *ill-posed*. No guarantee of a global well-defined, stable, and unique solution! Nonlocal constraints yield the existence, uniqueness & stability of local and global solutions to the *ultrahyperbolic wave equation* under Cauchy initial data.



Spacekime Wave Equ Sol

$$\underbrace{\sum_{i=1}^{d_s} \partial_{x_i}^2 u}_{\text{spacial Laplacian}} := \Delta_x u(x, \kappa) = \Delta_\kappa u(x, \kappa) =: \underbrace{\sum_{i=1}^{d_t} \partial_{\kappa_i}^2 u}_{\text{temporal Laplacian}}, \quad \begin{cases} u_0 = u(x \in D_s; (0, \kappa_{-1}) \in D_t) \\ u_1 = \partial_{\kappa_1} u(x, (0, \kappa_{-1})) \end{cases}$$

initial conditions (Cauchy data)

$\exists$  stable local solution over a Fourier frequency region, nonlocal constraints,  $|\xi| \geq |\eta_{-1}|$ .

$$\hat{u}(\xi, \kappa_1, \eta_{-1}) = \cos(2\pi\kappa_1 \sqrt{|\xi|^2 - |\eta_{-1}|^2}) \hat{u}_0(\xi, \eta_{-1}) + \sin(2\pi\kappa_1 \sqrt{|\xi|^2 - |\eta_{-1}|^2}) \frac{\hat{u}_1(\xi, \eta_{-1})}{2\pi \sqrt{|\xi|^2 - |\eta_{-1}|^2}}$$

Craig & Weinstein (2008); Wang et al. (2022); Dinov & Velev (2021).

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## Kime manifold, metric, and cone measure

- Domain:  $\mathcal{M} = (0, T] \times \mathbb{S}^1$  with cone metric

$$g_0 = dt^2 + t^2 d\theta^2.$$

- Natural measure (cone measure):

$$d\mu_{g_0} = t dt \otimes \frac{d\theta}{2\pi}.$$

- Hilbert space:

$$\mathcal{H} = L^2(\mathcal{M}, d\mu_{g_0}).$$

### Remark

The geometry induces the correct inner products, Sobolev penalties, and spectral regularization aligned with polar coordinates.

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## Laplace-Beltrami operator on the cone

On  $(\mathcal{M}, g_0)$ , the Laplace-Beltrami operator is

$$\Delta_{g_0} = \frac{1}{t} \frac{\partial}{\partial t} \left( t \frac{\partial}{\partial t} \right) + \frac{1}{t^2} \frac{\partial^2}{\partial \theta^2}.$$

- Used to motivate smoothness penalties and spectral bases.
- Eigenstructures connect to Bessel functions (regularity at  $t = 0$ , boundary at  $t = T$ ).
- Enables anisotropic regularization aligned with the cone geometry (future extensions).

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## Harmonic expansions and kime-surface representation

Represent the kime-surface and phase law using harmonics in  $\theta$ :

$$S(t, \theta) = \sum_{n \in \mathbb{Z}} f_n(t) e^{in\theta}, \quad f_{-n}(t) = \overline{f_n(t)},$$

$$\varphi_t(\theta) = \sum_{n \in \mathbb{Z}} \widehat{\varphi}_t(n) e^{in\theta}, \quad \widehat{\varphi}_t(0) = 1.$$

Truncation to  $n \in \{-J, \dots, J\}$  yields efficient computation and controlled bias.

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## Mixed moments and posterior harmonics (KPT E-step objects)

For Gaussian likelihood  $Y | \theta \sim N(S(t, \theta), \sigma^2)$ :

$$p(\theta | y; t) \propto \varphi_t(\theta) \exp\left(-\frac{(y - S(t, \theta))^2}{2\sigma^2}\right).$$

Define posterior harmonic expectations

$$\xi_{j,k}(n) = \mathbb{E}\left[e^{-in\Theta_{j,k}} | y_{j,k}\right] = \int_0^{2\pi} e^{-in\theta} p(\theta | y_{j,k}; t_k) \frac{d\theta}{2\pi}.$$

Empirical mixed moments:

$$\widehat{m}_n(t_k) = \frac{1}{N} \sum_{j=1}^N y_{j,k} \xi_{j,k}(n).$$

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## Key spectral factorization: convolution $\rightarrow$ product

Define generating functions (or Fourier series on the unit circle):

$$M(z, t) = \underbrace{\sum_n m_n(t) z^n}_{FT(\text{mixed-moments})}, \quad F(z, t) = \underbrace{\sum_n f_n(t) z^n}_{FT(\text{kime-surface})}, \quad \Phi(z, t) = \underbrace{\sum_n \widehat{\varphi}_t(n) z^n}_{FT(\text{phase})}, \quad |z| = 1.$$

**Core KPT identity (on  $|z| = 1$ )**

$$M(z, t) = F(z, t) \Phi(z, t).$$

- Mixed moments are a convolution in  $n$ , which becomes pointwise multiplication in the generating-function / DFT domain.
- Enables regularized deconvolution updates for  $\Phi$  and  $F$ .

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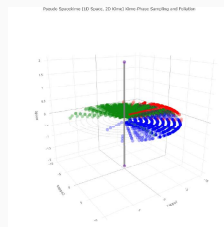
## Gauge (rotation) ambiguity and anchoring

A joint circular shift  $\theta \mapsto \theta + \alpha(t)$  induces

$$\varphi_t(\theta) \mapsto \varphi_t(\theta - \alpha(t)), \quad S(t, \theta) \mapsto S(t, \theta - \alpha(t)),$$

leaving the composed signal distribution invariant.

- **Rotation-invariant functionals:**  $|\widehat{\varphi}_t(n)|$ , Sobolev energies, distances.
- **Directional functionals:** mean direction, V-tests, phase-aligned comparisons require anchoring.
- **Anchoring rule (example):** choose  $n_* \geq 1$  with  $|\widehat{\varphi}_t(n_*)| > 0$  and rotate so  $\widehat{\varphi}_t(n_*)$  is real and  $> 0$ .



Three Longitudinal Processes over the Kime manifold.

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## 3. Inference and Space-Kime Analytics

## Inference from KPT outputs

Given estimated phases,  $\widehat{\varphi}_{t,estim}(\theta)$ , or their Fourier coefficients,  $\widehat{\varphi}_{t,FT}(n)$ , we perform

- **Uniformity tests** (Rayleigh-type based on first harmonic magnitude).
- **Directional alternatives** (V-test; requires anchoring).
- **Two-sample comparisons** via weighted Fourier distances.
- **Across-time inference** with multiplicity control over  $\{t_k\}$ .
- **Uncertainty quantification** via spectral delta method and/or bootstrapping.

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## Regularization-induced shrinkage and de-biasing

Let  $\Lambda_p(\omega) = (2 \sin(\frac{\omega}{2}))^{2p}$  be the discrete Sobolev weight of order  $p \in \{0, 1, 2\}$ . A Wiener-Sobolev update implies shrinkage factor

$$H(\omega, t) = \frac{|\widehat{F}(\omega, t)|^2}{|\widehat{F}(\omega, t)|^2 + \lambda_\Phi \Lambda_{p_\Phi}(\omega)} \in (0, 1].$$

De-biased spectrum (when stable):

$$\widetilde{\Phi}(\omega, t) = \frac{\widehat{\Phi}(\omega, t)}{H(\omega, t)} = \frac{\widehat{F}(\omega, t)}{|\widehat{F}(\omega, t)|^2} \widehat{M}(\omega, t) \quad (\text{optionally with ridge}).$$

- Extract first harmonic (or other modes) from  $\widetilde{\Phi}$  for asymptotic calibration.
- If  $|\widehat{F}|$  is small, prefer bootstrap calibration.

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## Space-kime analytics (SKA): spatial extension

Let observations be indexed by spatial location  $s$  (voxel, pixel, sensor, region).

$$y_{j,k}(s) = \mathcal{S}(t_k, \Theta_{j,k}(s); s) + \varepsilon_{j,k}(s), \quad \Theta_{j,k}(s) \sim \varphi_{t_k}(\cdot; s).$$

- Estimate  $\widehat{\varphi}_t(\theta; s)$  and  $\widehat{\mathcal{S}}(t, \theta; s)$  across  $s$ .
- Spatial regularization on harmonic coefficients (optional).
- Outputs: maps of phase concentration, drift, multimodality; phase-conditioned response maps.

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## 4. Applications and Validation (Simulations)

## Validation protocol: two motivating case studies

- **Simulation Study I:** quantum double-slit experiment with run-to-run phase variability.
- **Simulation Study II:** synthetic event-related fMRI ON-OFF design with time-varying latent physiological state.
- Both demonstrate core tenet: *apparent noise* can be decomposed into extrinsic noise + intrinsic kime-phase variability.

### Reproducibility

End-to-end computational protocol and figures are provided in the supplemental Rmd notebook / supporting website.

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## Double-slit: qualitative reconstruction of kime-surface

- Recover  $\widehat{\mathcal{S}}(t, \theta)$  from repeated noisy observations.
- Compare true vs. KPT-GEM and KPT-FFT reconstructions.

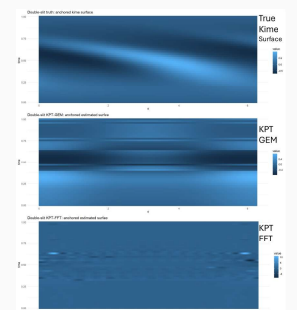


Figure: True vs. KPT reconstructions of  $\mathcal{S}(t, \theta)$ .

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## Double-slit: phase recovery metrics across time

Time-varying KL/JSD/Hellinger/TV between true  $\varphi_t$  and estimated  $\hat{\varphi}_t$ .

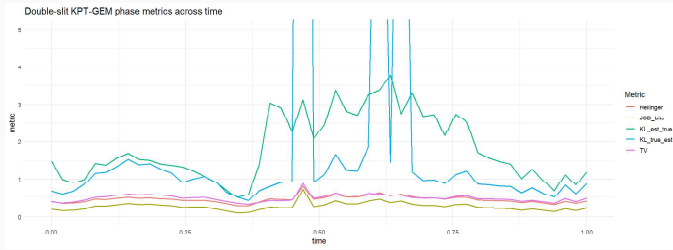


Figure: Phase metrics across time (KPT-GEM).

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## Double-slit: predictive fit and confidence bands

Compare mean MAP curves and confidence bands to observed scatter.

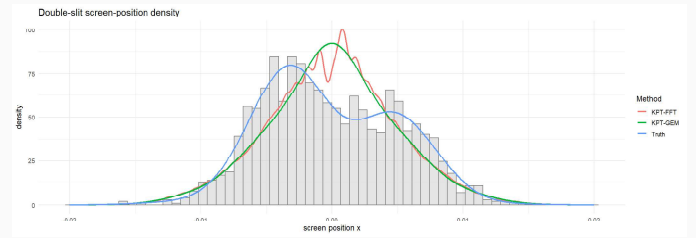


Figure: Phase metrics across time (KPT-GEM).

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## Double-slit: summary metrics

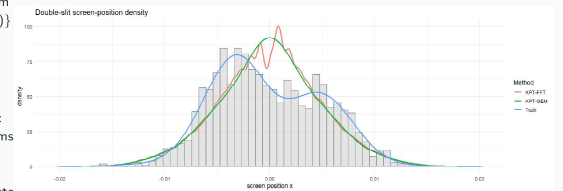
Table: Double-Slit Experiment: Summary metrics comparing true kime-surface vs. KPT reconstructions (KPT-GEM, KPT-FFT).

| Algorithm | Mean JSD (bits) | Mean Hellinger | Mean TV | Rel. L2 Surface |
|-----------|-----------------|----------------|---------|-----------------|
| KPT-GEM   | 0.2629          | 0.4474         | 0.4861  | 1.0896          |
| KPT-FFT   | 0.5213          | 0.6490         | 0.6846  | 1.9756          |

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## Double-slit: posterior predictive position density (physics linkage)

- Use KPT-estim  $\{\hat{S}(t, \theta), \hat{\varphi}_t(\theta)\}$  to predict screen-hit position distribution.
- Interpretation: KPT transforms run-to-run interference fluctuations into an inferred phase law and a deterministic kime-surface.



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## fMRI simulation: setup and motivation

- Simulate event-related ON vs. OFF fMRI design with repeated runs per participant.
- Input to KPT: difference signal  $y_{j,r,k} = \text{ON}_{j,r,k} - \text{OFF}_{j,r,k}$  to isolate task activation.
- KPT hypothesis: substantial run-to-run variability arises from intrinsic physiological state, modeled as latent kime-phase  $\Theta(t)$ .

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## fMRI: raw simulated trajectories

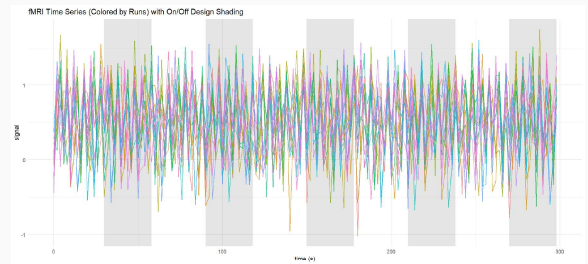


Figure: Examples of simulated ON and OFF fMRI time-courses for random participants (P) and runs (R).

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## fMRI: phase recovery metrics across time

fMRI KPT-GEM performance: phase recovery metrics between true & estimated  $\varphi_t$

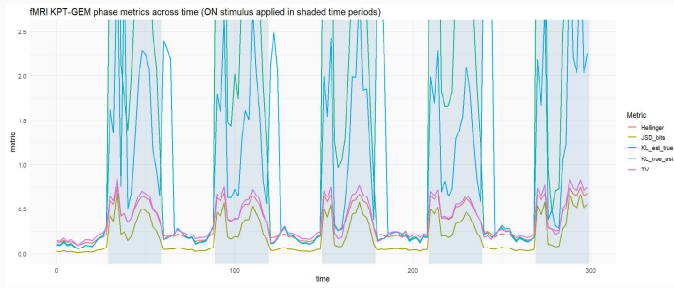


Figure: fMRI KPT-GEM performance, phase recovery metrics across time.

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## fMRI: example phase at a fixed time slice

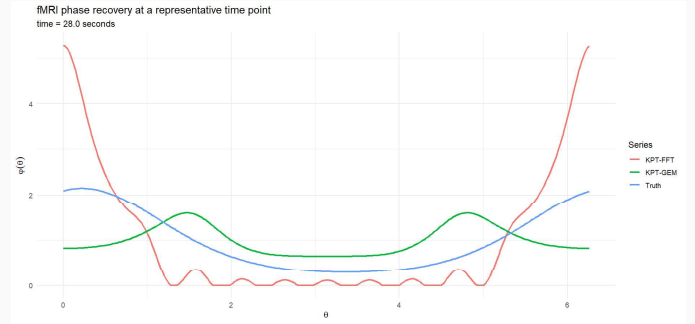


Figure: True phase  $\varphi_{t=28s}$  vs. KPT-estimated phases at the same time.

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## fMRI: kime-surface heatmaps (polar) and 3D reconstructions

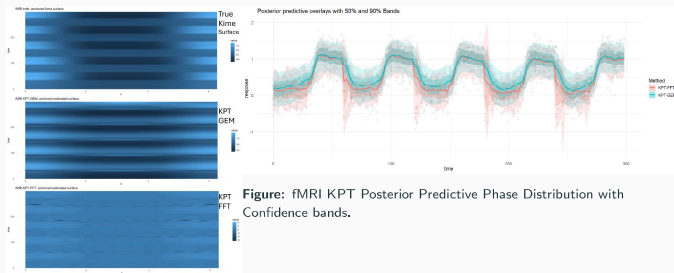


Figure: fMRI KPT Posterior Predictive Phase Distribution with Confidence bands.

Figure: Polar heatmaps of true vs. KPT kime-surfaces.

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## fMRI Experiment: summary metrics

Table: fMRI Experiment: Summary metrics comparing true kime-surface vs. KPT reconstructions (KPT-GEM, KPT-FFT).

| Algorithm | Mean JSD (bits) | Mean Hellinger | Mean TV | Rel. L2 Surface |
|-----------|-----------------|----------------|---------|-----------------|
| KPT-GEM   | 0.1952          | 0.3455         | 0.3737  | 1.4639          |
| KPT-FFT   | 0.1881          | 0.3672         | 0.3811  | 1.0585          |

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## 5. Limitations and Opportunities

## Advantages of complex-time kime-representation & KPT reconstruction

- **Beyond averaging:** explains replicate variability as structured latent state distribution  $\varphi_t$ .
- **More than warping:** phase is learned as a *distribution* (can be multimodal), not a single alignment map.
- **Beyond generic state-space:** explicit spectral deconvolution ( $M = F\Phi$ ) yields fast closed-form updates and interpretable components.
- **More than black-box deep models:** provides geometry, constraints, and inferential targets with uncertainty quantification hooks.

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## KPT limitations and practical considerations

- Likelihood assumptions (e.g., Gaussian) and noise estimation can impact E-step posterior moments.
- Deconvolution ill-conditioning when  $|F(\omega, t)|$  is small (use ridge, bootstrap, or temporal coupling).
- Truncation  $J$  trades bias and variance; regularization  $(\lambda, p)$  must be tuned (cross-validation, predictive criteria, bootstrap).
- Directional inference requires anchoring; rotation-invariant comparisons avoid this.
- Extensions: non-Gaussian likelihoods (counts), heavy-tailed noise, anisotropic penalties in  $(t, \theta)$  aligned with  $\hat{g}_0$ .

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## Other Applications

- **Neuroimaging / clinical trials:** run-to-run variability decomposition; QC and stability biomarkers (space-kime maps).
- **Quantum sensing / interferometry:** phase drift tomography and predictive distributions for detection patterns.
- **Coherent imaging / microscopy:** phase-aware stabilization; uncertainty-aware reconstructions.
- **Industrial IoT:** phase-state monitoring for cyclic processes and predictive maintenance.
- **Digital health:** latent physiological state distributions and personalized baselines.

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## 6. Summary

## Key takeaways

- Kime representation augments *classical time* with a latent *phase* to account and model structured replicate variability.
- Based on replicated longitudinal process measurements and the spectral factorization  $M = F\Phi$ , KPT reconstructs

$$\left( \underbrace{S(t, \theta)}_{\text{kime surface}}, \underbrace{\varphi_t(\theta)}_{\text{phase law}} \right)$$

- In practice, FFT-based Wiener-Sobolev updates provide scalable computation with principled regularization.
- *KPT outputs* enable inference (uniformity, two-sample, longitudinal), prediction, and space-kime mapping.

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## Resources and reproducibility

Websites: <https://TCIU.predictive.space/> | <https://Spacekime.org/>  
Rmd-notebook: [https://socr.umich.edu/TCIU/HTMLs/TCIU.SK\\_Appendix03.KPT\\_DS\\_fMRI\\_V5.html](https://socr.umich.edu/TCIU/HTMLs/TCIU.SK_Appendix03.KPT_DS_fMRI_V5.html)

The screenshot shows a Jupyter notebook with a table of contents on the left and the main content on the right. The table of contents includes sections like '1 Introduction', '2 Mathematical Framework', '2.1 KPT Inverse Problem', '2.2 KPT Algorithms', '2.2.1 Algorithm 1: KPT-GEM (Generalized EM)', '2.2.2 Algorithm 2: KPT-FFT (Fully Alternating)', '3 Implementation', '3.1 Core Utilities', '3.2 Unified KPT Implementation', '4 Double-Slit Experiment (with Phase Alignment)', '4.1 Setup and Utilities', '4.2 Double-Slit Simulation', '4.3 Run KPT with Proper Alignment', '4.4 Quantitative Evaluation (Post-Alignment)', '4.5 Visualization (Aligned Results)', and '4.6 Kime-Surface Comparison'. The main content area shows the title 'Time Complexity, Inferential uncertainty and Spacekime Analytics' and the start of 'Appendix 03: Kime-Phase Tomography (KPT V.5: KPT-GEM & KPT-FFT): fMRI and Double-Slit Validation' by the SOCR Team, dated 01/03/2026. It includes a link to a GitHub repository and a brief description of the notebook's purpose.

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- Thank you to many SOCR collaborators, other contributors to the KPT theory, algorithms, and validation protocols, and the broader open-science community.
- Contact: [statistics@umich.edu](mailto:statistics@umich.edu).



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